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exercises can be used with the MATLAB Robotics Toolbox2 created by Peter Corke, Principal Research Scientist with CSIRO in Australia. Chapter 1 is an introduction to the field of robotics. It introduces some background material, a few fundamental ideas, and the adopted notation of the book, and it previews the material in the later chapters.

Introduction to Robotics - Mechanical Engineering

Since its original publication in 1986, Craig ' s Introduction to Robotics: Mechanics and Control has been the leading textbook for teaching robotics at the university level. Blending traditional mechanical engineering material with computer science and control theoretical concepts, the text covers a range of topics, including rigid-body transformations, forward and inverse positional kinematics, velocities and Jacobians of linkages, dynamics, linear and non-linear control, force control ...

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Synopsis. For senior-year or first-year graduate level robotics courses generally taught from the mechanical engineering, electrical engineering, or computer science departments. Since its original publication in 1986, Craig's Introduction to Robotics: Mechanics and Control has been the market's leading textbook used for teaching robotics at the university level.

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